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# Seventh Semester B.Tech. Degree Examination, June 2016 (2008 Scheme)

08.702 : MECHATRONICS (MPU)

Time: 3 Hours

Max. Marks: 100

## PART-A

Answer all questions. 4 marks each.

1. Define hysteresis in sensors. Give one example.



- 2. What is meant by resolution of incremental encoder? How the resolution can be improved for it?
- 3. Write two applications for piezoelectric effect in sensors.
- Sketch a schematic diagram and hydraulic symbol for pressure sequence valve.
  Write the functioning.
- 5. What are positive and negative photo resists in MEMS fabrication?
  - 6. What is meant by 'stick-slip' in friction guideways? How this effect can be reduced?
  - 7. Distinguish between hydrostatic and hydrodynamic bearings.
  - 8. Describe the architecture of PLC.
  - 9. What is tactile sensing? Give examples.
  - 10. What is meant by 'thresholding' of histogram?

(4×10=40 Marks)



#### PART-B

Answer one complete question from each Module:

#### Module - 1

- 11. a) Illustrate the functioning and application for synchros and resolves.
  - b) Explain vibration sensors.

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- 12. a) Discuss the methods of temperature sensing.
  - b) Describe the principle, construction and working of MEMS gyroscope.

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### Module - 2

- 13. a) What are the types of loads to be considered in designing the structure of CNC machine tools? Explain its influence.
  - Explain the construction and functioning of recirculating fall screws used in CNC machines.

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- 14. a) Explain the types of adaptive controls used in mechatronic systems.
  - b) Develop a mathematical model for any thermal system under conductive heat transfer.

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### Module - 3

- 15. a) Explain the working of permanent magnet stepper motor.
  - b) Discuss any two types of range finding techniques used in robotics.

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- a) Develop a schematic diagram, to sense the level of liquid in a shallow containe using a magnetism based proximity sensor.
  - b) List the names and functioning of typical sensors used in automobile engine management system.

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(20x3=60 Marks)

(Ax10=01xA)

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